Noise sensitivity from fractional query algorithms

Renan Gross, Weizmann Institute of Science

## Boolean functions

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Example: Majority

$$
f(x)=\operatorname{sign} \sum_{i=1}^{n} x_{i}
$$



## Percolation

$$
f:\{-1,1\}^{n} \rightarrow\{-1,1\}
$$



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f:\{-1,1\}^{n} \rightarrow\{-1,1\}
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$$
\mathrm{x}=1,1,-1,1,-1,-1,-1,-1,-1,1,1,-1,1,-1, \ldots
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## Percolation <br> $$
f(x)=\left\{\begin{aligned} 1 & \text { if green } \uparrow \text { crossing } \\ -1 & \text { if yellow } \leftrightarrow \text { crossing } \end{aligned}\right.
$$



Noise sensitivity


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Pick $\varepsilon>0$, and flip each bit with probability $\varepsilon$.
Did the function's value change?

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Definition: A sequence $f_{n}:\{-1,1\}^{n} \rightarrow\{-1,1\}$ of balanced Boolean functions is called "noise sensitive" if for all $\varepsilon>0$,

$$
\lim _{n \rightarrow \infty} \mathbb{E}\left[f_{n}(x) f_{n}(y)\right]=0,
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where $x$ is random and $y$ is an $\varepsilon$-noising of $x$.

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Is percolation crossing noise sensitive?
If so, how fast can $\varepsilon$ go to 0 with $n$ ?

## Decision trees

$x$ is uniform random, but hidden from you. Reveal hexagons one by one, until $f(x)$ is found.


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The faster $\delta \rightarrow 0$, the more noise sensitive it is!

## The interface algorithm



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## Fractional query algorithms

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## View 1:

| True $x$ | 1 | -1 | 1 | -1 | -1 | 1 | 1 | -1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

## Fractional query algorithms

## View 1:

True $x$

$$
\begin{array}{ll|llllll}
1 & -1 & 1 & -1 & -1 & 1 & 1 & -1
\end{array}
$$

Known $x$
? ? $\quad$ ? $\quad$ ? $\quad$ ? $\quad ? \quad$ ?

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$$
\begin{array}{|c|c|c|c|c|c|c|c|}
\hline 1 & -1 & 1 & -1 & -1 & 1 & 1 & -1 \\
\hline ? & ? & & & ? & ? & ? & ? \\
\hline ? & ? & ? & ? & \\
\hline
\end{array}
$$

Known $x$

## Fractional query algorithms

 View 1:True $x$

Known $x$ $\square$

View 2:

Input $x$

| $?$ | $?$ | $?$ | $?$ | $?$ | $?$ | $?$ | $?$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

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Known $x$


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Known $x$

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| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $?$ | $?$ | 1 | $?$ | $?$ | $?$ | $?$ | $?$ |

View 2:

Input $x$

$$
\begin{array}{rl}
? & ? \\
? & ?
\end{array} ? \quad ? \quad ? \quad ?
$$

## Fractional query algorithms Input $\boldsymbol{x}(\boldsymbol{t})$ is a stochastic process!

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## Fractional query algorithms

 Input $\boldsymbol{x}(\boldsymbol{t})$ is a stochastic process!| $x(0)$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $x(1)$ | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

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| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
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| $x(2)$ | 0 | 0 | 0 | 1 | 0 | -1 | 0 | 0 |

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| $x(1)$ | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| $x(2)$ <br> $\vdots$ | 0 | 0 | 0 | 1 | 0 | -1 | 0 | 0 |
| $x(\tau)$ |  | 1 | 0 | 0 | 1 | 0 | -1 | -1 |$|$| 1 |
| :---: |

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| $\vdots$ |  |  |  | $\vdots$ |  |  |  |  |
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## Fractional query algorithms

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| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $x_{i}=x_{i}+\left\{\begin{array}{r} \varepsilon \text { w.p. } 1 / 2 \\ -\varepsilon \text { w.p. } 1 / 2 \end{array}\right.$ |  |  |  |  |  |  |  |

$x(1)$

| 0 | 0 | $\varepsilon$ | 0 | 0 | 0 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

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$x(2)$

| 0 | 0 | $\varepsilon$ | $-\varepsilon$ | 0 | 0 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

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| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
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$\begin{array}{ll}0 & 0 \\ & \end{array}$

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$x(3)$

| 0 | 0 | 0 | $-\varepsilon$ | 0 | 0 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

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$x(3)$

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| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Can only do this if $x_{i}(t) \in(-1,1)$.

## Computing with fractional inputs

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Every $f:\{-1,1\}^{n} \rightarrow\{-1,1\}$ can be written as

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The current value gives a hint to the future:

$$
\mathbb{P}\left[X_{i}(\infty)=1 \mid X_{i}(t)\right]=\frac{1+X_{i}(t)}{2}
$$

## Comparing with classical algorithms

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For classical decision trees,

$$
\delta_{i}=\mathbb{P}[\text { bit } i \text { is queried }]=\mathbb{E}\left[X_{i}(\tau)^{2}\right]
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Fact: $\min _{\varepsilon-\text { algs }} \delta_{i} \leq \min _{2 \varepsilon-\text { algs }} \delta_{i}$

$$
\begin{gathered}
x-2 \varepsilon \quad x \quad x+2 \varepsilon \\
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Why this cost?

$$
\begin{array}{cc}
x-2 \varepsilon \quad x \quad x+2 \varepsilon \\
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x-\varepsilon \quad x+\varepsilon
\end{array}
$$

Fact: $\mathbb{E}\left[X_{i}(\tau)^{2}\right]=\mathbb{E}\left[X_{i}\right]_{\tau}=\varepsilon^{2} \mathbb{E}[\#$ times $i$ was chosen $]$

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## Sending $\varepsilon \rightarrow 0 \quad\left(u_{s}(x)=\min _{i} \frac{u_{\varepsilon}\left(x+\varepsilon \varepsilon_{i}\right)+u_{c}\left(x-\varepsilon \varepsilon_{i}\right)}{2}+\varepsilon^{2}\right)$

## Sending $\varepsilon \rightarrow 0 \quad\left(u_{c}(x)=\min _{p} \frac{u_{( }\left(x+\varepsilon(\varepsilon)+u_{c}(x-\varepsilon \varepsilon)\right.}{2}+\varepsilon^{2}\right)$

Theorem: Define $u=\lim _{\varepsilon \rightarrow 0} u_{\varepsilon}$. Then

$$
\min _{i} \frac{\partial^{2} u}{\partial x_{i}^{2}}+2=0
$$

- "Axis-aligned Laplacian" equation.


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- "Axis-aligned Laplacian" equation.
- $u(0)$ might tell us something about $\delta$ !
- Solving a PDE can give us noise-sensitivity.


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## The big question

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- Is $P=N P$ ?


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-TSP-NP?

- Is there a class of functions $f$ such that

$$
\lim _{n \rightarrow \infty} \liminf _{\varepsilon \rightarrow 0} \frac{\delta(f, \varepsilon)}{\delta(f, 1)}=0 ?
$$

(specifically, what about percolation?)

## Overview

- Boolean functions, noise-sensitivity, revealment algorithms
- Fractional algorithms can do better

- A limiting partial differential equation

$$
\min _{i} \frac{\partial^{2} u}{\partial x_{i}^{2}}=-2
$$





Also a tree


